

PRAM 和 LARPBS 模型上有向序列翻转距离并行算法*

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Parallel Algorithms for Reversal Distance of Permutations on PRAM and LARPBS

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Abstract: This paper presents two parallel algorithms to compute reversal distance of two signed permutations on different models. These two algorithms are based on Hannenhalli and Pevzner's theory and composed of three key steps: Construct break point graph, compute the number of cycles in break point graph and compute the number of hurdles in break point graph. The first algorithm runs in $O(\log^2 n)$ time using $O(n^2)$ processors in SIMD-CREW model. The second one can solve the problem in $O(\log n)$ bus cycles by using $O(n^3)$ processors on the linear array with a reconfigurable pipelined bus system (LARPBS).

Key words: parallel algorithm; optical bus parallel model; reversal distance; genome rearrangements; sequence comparison; CREW-PRAM model

摘要: 分别在两种重要并行计算模型中给出计算有向基因组排列的反转距离新的并行算法.基于Hannenhalli和Pevzner理论,分3个主要部分设计并行算法:构建断点图、计算断点图中圈数、计算断点图中障碍的数目.在CREW-PRAM模型上,算法使用 $O(n^2)$ 处理器,时间复杂度为 $O(\log^2 n)$;在基于流水光总线的可重构线性阵列系统(linear array with a reconfigurable pipelined bus system, LARPBS)模型上,算法使用 $O(n^3)$ 处理器,计算时间复杂度为 $O(\log n)$.

关键词: 并行算法;光总线并行模型;反转距离;基因组重排;序列比较;CREW-PRAM模型

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1 Introduction

Computing reversal distance of two signed permutations has gained increasing attention over the last decade

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with the study of genome rearrangements in computational molecular biology. It plays an important role in checking DNA sequences similarity at the level of genome and finding evolutionary relationship between species.

A signed permutation is a permutation $\pi = \{\pi_1, \pi_2, \dots, \pi_n\}$ on the set of integers $\{1, 2, \dots, n\}$ whose each element has a sign of plus or minus. A reversal $\rho(i, j)$ on permutation π transforms π to

$$\pi' = \pi \rho(i, j) = \{\pi_1, \dots, \pi_{i-1}, -\pi_i, -\pi_{i+1}, \dots, -\pi_{j-1}, -\pi_j, -\pi_{j+1}, \dots, \pi_n\} \quad (1)$$

The reversal distance of two permutations is the minimum number of reversals needed to transform one to another permutation. The problem of computing reversal distance of permutation π is to find the minimum number of reversals needed to transform π to identical permutation $\{1, 2, \dots, n\}$.

In 1995, Hannenhalli and Pevzner^[1,2] built a basic theory about how a signed permutation is sorted by reversals and gave the first polynomial-time algorithm to solve the problem of sorting a signed permutation by reversals, which runs in $O(n^2)$ time when restricted to distance computation. In 1996, a $O(n^2 \alpha(n))$ reversal sorting algorithm was given by Berman and Hannenhalli^[3], where $\alpha(n)$ is the Ackerman's function, it also provided the distance as a byproduct. Bader, Moret and Yan^[4] showed how to compute reversal distance in the linear time. More recently, Bergeron^[5] presented another $O(n)$ time algorithm for problem of reversal distance.

In this paper we present two parallel algorithms for computing reversal distance of a signed permutation of n elements that are based on Hannenhalli and Pevzner's theory and composed of three steps. The first algorithm consists three parts and runs in $O(\log^2 n)$ time using $O(n^2)$ processors in SIMD-CREW model^[9]. The second one can solve the problem in $O(\log n)$ bus cycles by using $O(n^3)$ processors on the Linear Array with a Reconfigurable Pipelined Bus System (LARPBS) which has been investigated in Ref.[6] for designing fast algorithms from different domains. To our best knowledge, this is the best time complexity parallel algorithm.

2 Preliminary Definitions

In this section we introduce the basic background for our algorithms. The exposition follows closely the Hannenhalli and Pevzner's theory^[1,2].

2.1 Basic definitions

Given a signed permutation π of $\{1, 2, \dots, n\}$, we transform it into an unsigned permutation π' of $\{1, 2, \dots, 2n-1, 2n\}$ by replacing each positive element x in π by $2x-1$ and $2x$, and each negative element x by $2x$ and $2x-1$, then extend permutation to the set $\{0, 1, \dots, 2n, 2n+1\}$ by setting $\pi_0=0$ and $\pi_{2n+1}=2n+1$. We represent an extended unsigned permutation with a *breakpoint graph* of the permutation. The breakpoint graph has $2n+2$ vertices; for each i , $1 \leq i \leq n$, we join vertices π_{2i} and π_{2i+1} by a black edge and vertices whose values are $2i$ and $2i+1$ by a gray edge. Notice that a gray edge (π_k, π_l) is oriented if the sum of $k+l$ is even, otherwise is unoriented. The resulting breakpoint graph consists of disjoint cycles in which edges alternate colors. A cycle in breakpoint graph is oriented if it has an oriented gray edge and unoriented otherwise.

Gray edges (π_i, π_j) and (π_k, π_l) are overlapping whenever the two intervals $[i, j]$ and $[k, l]$ overlap, but neither contains the other. The overlap graph of a permutation π , denoted by $OV(\pi)$, is the overlap graph of the gray edges of $B(\pi)$. In other words, the node set of $OV(\pi)$ is the set of gray edges in $B(\pi)$, and two nodes are connected by an arc if two gray edges overlap. We shall identify a node in $OV(\pi)$ with the edge it represents and with its interval in the representation. Thus, the endpoints of a gray edge are actually the endpoints of the interval representing the corresponding node in $OV(\pi)$. A connected component of $OV(\pi)$ that contains an oriented edge is called an oriented component, otherwise, it is called an unoriented component.

Let M be an unoriented connected component in $OV(\pi)$. Let $E(M)$ be the set of end points of the edges in M . An unoriented component of π is a *hurdle* if the elements belonged to $E(M)$ occur consecutively, in the other words, the

elements belonged to $E(M)$ must be an interval from i to $(i+j)$ or from i to $(i+j) \bmod n$, whose set of elements is $(i, \dots, i+j)$ but not in a single two-edged circle components. A hurdle is a *simple hurdle* if when one deletes it from $OV(\pi)$ no other unoriented component becomes a hurdle, otherwise is a *super hurdle*. Permutation π is called *fortress* if it has an odd number of hurdles and all these hurdles are super hurdles (Fig.1).

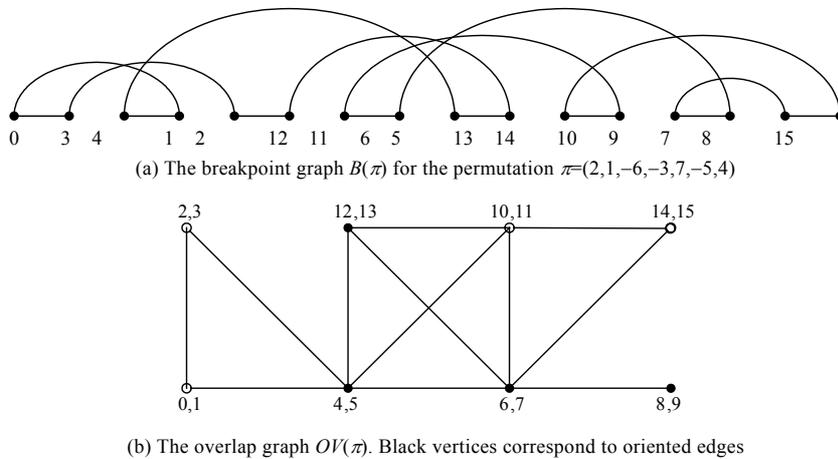


Fig.1

Lemma 1. For a signed permutation π of order n , $d(\pi)=n-c(\pi)+h(\pi)+f(\pi)$, where $c(\pi)$, $h(\pi)$ and $f(\pi)$ are the numbers of cycles, hurdles and, fortress in the breakpoint graph of the permutation π .

2.2 The LARPBS model

The LARPBS model connects its processors by an optical bus that uses optical waveguide instead of electrical bus to transfer messages among processors. The advantages of using optical waveguide are high propagation speed, unidirectional propagation and predictable propagation delay per unit length. The last two properties enable synchronized concurrent accesses of an optical bus in a pipelined fashion.

LARPBS can be partitioned into $i \geq 2$ independent subarrays, such those subarrays can be operated as regular linear arrays with pipelined optical bus systems, and all subarrays can be used independently for different computations without interference^[6,7,9](Fig.2).

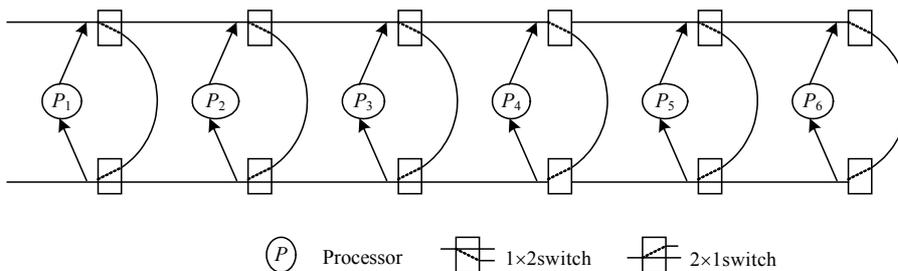


Fig.2 (Source [7]) The LARPBS model of size 6 with two subarrays

The measure of computational complexity on a LARPBS is the number of bus cycles used for the computation and the amount of time spent by the processors for local computations. A bus cycle is the time needed for end-to-end message transmission over a bus and assumed to take only $O(1)$ time.

The following basic communication, data movement, and global operations on the LARPBS are used in this

paper. The reader is referred to [6,7,9] for the implementation details of these operations.

Lemma 2^[6,7,9]. One-to-One communication, broadcasting, multicasting and multiple multicasting, all can be done in $O(1)$ bus cycles on the LARPBS model.

Lemma 3^[6,7,9]. For a LARPBS with n processors and n binary values v_i , $0 \leq i \leq n-1$, the binary prefix sum requires the computation of $psum_i = v_0 + v_1 + \dots + v_{i-1}$, for all $0 \leq i \leq n-1$. It can be done in $O(1)$ bus cycles on the LARPBS model.

Lemma 4^[9]. Sorting n numbers can be performed in $O(1)$ bus cycles on the LARPBS model with $O(n^2)$ processors.

3 Algorithms

In this section, the complete algorithms for computing reversal distance are presented.

The Complete Algorithm Framework.

Input: Signed permutation π ,

Output: Reversal distance of permutation π .

Step 1. Construct break point graph $B(\pi)$ of permutation π (Algorithm 1, Fig.3);

Step 2. Compute the number $c(\pi)$ of cycles in $B(\pi)$ (Algorithm 2, Fig.4);

Step 3. Construct overlap graph $OV(\pi)$ of permutation π based on break point graph $B(\pi)$ built in Step1; find all components in $B(\pi)$ and compute the number $h(\pi)$ of hurdles in $B(\pi)$;

Step 4. Determine whether breakpoint graph $B(\pi)$ is a fortress $f(\pi)$ and compute the reversal distance of π , $d(\pi) = n - c(\pi) + h(\pi) + f(\pi)$.

Algorithm 1. Construct breakpoint graph

Input: Permutation;

Output: Breakpoint graph of permutation.

```

1  for each  $i: 1 \leq i \leq n$  pardo
2    if  $\pi_i > 0$  then
3       $a_{2i-1} \leftarrow 2\pi_i - 1, a_{2i} \leftarrow 2\pi_i$ 
4    else
5       $a_{2i-1} \leftarrow 2|\pi_i|, a_{2i} \leftarrow 2|\pi_i| - 1$ 
6    endif
7  endfor
8   $a_0 \leftarrow 0, a_{2n-1} \leftarrow 2n+1$ 
9  for each  $i: 1 \leq i \leq n$  pardo
10   connect  $(a_{2i}, a_{2i+1})$  with a black edge
11 endfor
12 for each  $i: 1 \leq i \leq n$  pardo
13    $b_{a_{2i}} \leftarrow 2i, b_{a_{2i-1}} \leftarrow 2i-1$ 
14 endfor
15 for each  $i: 1 \leq i \leq n$  pardo
16   connect  $(a_{b_{2i}}, a_{b_{2i-1}})$  with a gray edge
17 endfor

```

Fig.3 The framework of Algorithm 1: construct breakpoint graph

Algorithm 1 constructs break point graph $B(\pi)$ of permutation π in parallel. The part of lines (1~8) in Algorithm 1 transforms permutation π into an unsigned permutation according to the precious definition. For each $i: 1 \leq i \leq n$, we join vertices a_{2i} and a_{2i+1} by a black edge (9~11). We also need join vertices whose values are $2i$ and $2i+1$ by a gray edge. Assume we need to connect $a_x = 2i$ and $a_y = 2i+1$, from lines (12~14) we can get $b_{2i} = x$ and $b_{2i+1} = y$ and connect $(a_{b_{2i}}, a_{b_{2i+1}})$ with a gray edge.

Algorithm 2 finds all cycles in the breakpoint graph $B(\pi)$ in parallel. In Algorithm 2, a cycle is labeled with the minimum vertex index of that cycle, and for each vertex π_i , we set $c(i)$ with the label of its cycle. Lines (1~3) are to initialize $c(i)$ with the vertex index; for the part of lines (4~16) in Algorithm 2, we use the point jumping method that is sufficed to show that, after k th iteration, for each vertex i , $c(i)$ must be the minimum vertex index within 2^k distance. It is easy to see that in each cycle, there is only one vertex whose index value($c(i)$) remains unchanged after the iteration part. We set $csum(i)=1$ if $c(i)=i$, otherwise $csum(i)=0$, then parallelly compute the sum of $csum(i)$.

By parallelly detecting every pair of edges ($O(n^2)$ pairs), the overlap graph $OV(\pi)$ can be built in $O(1)$ time using $O(n^2)$ processors. The method to find components used by Algorithm 3 is similar to Algorithm 2. Because each node in $OV(\pi)$ has at most $O(n)$ adjacent nodes, there remain some differences: line 7 and Algorithm 3 need to find the minimum number in $O(n)$ numbers; to avoid writing confliction, we specify an array in each node. For any node j , if $d(j)<c(c(j))$: $c(j)=i$, we set $w_i(j)=d(j)$ at node i (lines 9~16)(Fig.5).

Algorithm 2. Find all cycles in breakpoint graph.

Input: Breakpoint graph;

Output: All cycles in breakpoint graph.

```

1  for each  $i: 1 \leq i \leq 2n+1$  pardo
2   $c(i) \leftarrow i$ 
3  endfor
4  repeat
5  for each  $i: 1 \leq i \leq 2n+1$  pardo
6   $d(i) \leftarrow \min\{c(j) | j \text{ are vertex adjacent to } i\}$ 
7  endfor
8  for each  $i: 1 \leq i \leq 2n+1$  pardo
9  if  $d(i) < c(c(i))$  then
10  $c(c(i)) \leftarrow d(i)$ 
11 endif
12 endfor
13 for each  $i: 1 \leq i \leq 2n+1$  pardo
14  $c(i) \leftarrow c(c(i))$ 
15 endfor
16 until all  $c(i)=d(i)$ 
17 for each  $i: 1 \leq i \leq 2n+1$  pardo
18  $csum(i) \leftarrow 0$ 
19 if  $c(i)=i$  then
20  $csum(i) \leftarrow 1$ 
21 endif
22 endfor
23 parallel computing sum of  $csum(i): 1 \leq i \leq 2n+1$ 

```

Fig.4 The framework of Algorithm 2:

Find all cycles in breakpoint graph

Algorithm 3. Find all components of permutation.

Input: Breakpoint graph;

Output: All components in breakpoint graph.

```

1  for each node  $i: 1 \leq i \leq n$  in  $OV(\pi)$  pardo
2   $c(i) \leftarrow \min\{b_i, e_i | b_i \text{ and } e_i \text{ are the endpoints of gray edge } i\}$ 
3  endfor
4   $a_0 \leftarrow 0, a_{2n-1} \leftarrow 2n+1$ 
5  repeat
6  for each node  $i: 1 \leq i \leq n$  in  $OV(\pi)$  pardo
7   $d(i) \leftarrow \min\{c(j) | j \text{ are node adjacent to } i\}$ 
8  endfor
9  for each node  $i: 1 \leq i \leq n$  in  $OV(\pi)$  pardo
10 if  $d(i) < c(c(i))$  then
11  $w_{c(i)}(i) \leftarrow d(i)$ 
12 endif
13 endfor
14 for each node  $i: 1 \leq i \leq n$  in  $OV(\pi)$  pardo
15  $c(i) \leftarrow \min\{w_i(j) | j: 1 \leq j \leq n\}$ 
16 endfor
17 for each node  $i: 1 \leq i \leq n$  in  $OV(\pi)$  pardo
18  $c(i) \leftarrow c(c(i))$ 
19 endfor
20 until all  $c(i)=d(i)$ 

```

Fig.5 The framework of Algorithm 3:

Find all components of permutation

3.1 Parallel algorithms on SIMD-CREW model

Theorem 1. Break point graph $B(\pi)$ of permutation π of $\{1, \dots, n\}$ can be constructed in a constant time using n processors on SIMD-CREW model.

Proof: In all parts of Algorithms 1, processors don't read and write the same memory places. It is easy to get that Algorithm 1 can run in a constant time using n processors on SIMD-CREW model. \square

Theorem 2. Finding all cycles in BP Graph takes $O(\log n)$ time using $O(n)$ processors on SIMD-CREW model.

Proof: The parts of lines (1-3) and (17-22) in Algorithm 2 both use $O(1)$ time; for the part of lines (4-16), after the k th iteration, for each vertex i , $c(i)$ will be the minimum vertex index within 2^k distance, and that is to say, after $O(\log l)$ iterations, each vertex of graph will be covered and each iteration uses a constant time. (l is the max

length of cycles, $l \leq n$.) The base case is trivial: parallel computing sum of n numbers runs $O(\log n)$ time with n processors on SIMD-CREW model. Algorithm 2 uses $O(\log n + \log l)$ (l at most is n) time, so the time complexity of Algorithm 2 is $O(\log n)$. \square

Theorem 3. Finding components in permutation π takes $O(\log^2 n)$ time using $O(n^2)$ processors on SIMD-CREW model.

Proof: As mentioned before, Line 1 in Algorithm 3 uses $O(1)$ time; Like Algorithms 2, after at most $O(\log n)$ iterations (lines 2~20), we can get the final result. The parts of lines (6~8) and (14~16) in iteration of Algorithm 3 need $O(\log n)$ time with n processors to compute the minimum number. The entire step uses $O(\log^2 n)$ time with $O(n^2)$ processors. \square

Lemma 5. Whether a component of $OV(\pi)$ is a hurdle can be determined in $O(\log n)$ time using $O(n)$ processors on SIMD-CREW model.

Proof: According to the definition of hurdle, we need two steps to test a component: first, checking whether the component is unoriented component just needs to know whether all edges are unoriented; second, checking if there is no other component between start and end of it except for two-edged simple cycles. Both steps can complete in a constant time with n processors in SIMD-CREW model. We gather all data in $O(\log n)$ time. \square

Theorem 4. The number of hurdles can be counted in $O(\log n)$ time with $O(n^2)$ processors on SIMD-CREW model.

Proof: There are at most $O(n)$ components in the permutation π . We can prove that all components can be determined in constant time using $O(n^2)$ processors as mentioned in Lemma 5. If a component is hurdle, we set $h(i)=1$, otherwise $h(i)=0$. Parallel computing sum of $h(i)$ takes $O(\log n)$ time with n processors. \square

Theorem 5. Whether the permutation is fortress can be determined in $O(\log^2 n)$ time with $O(n^2)$ processors on SIMD-CREW model.

Proof: We delete all hurdles, and then compute the number of hurdles in the remaining graph. If the number of hurdles in the remaining graph is equal to the number before deleting and the number is odd, $f(\pi)=1$. That can be completed in $O(\log^2 n)$ time with n^2 processors on SIMD-CREW model. \square

Theorem 6. Computing reversal distance of permutation π takes $O(\log^2 n)$ time with $O(n^2)$ processors on SIMD-CREW model.

Proof: The steps of the algorithm at most take $O(\log^2 n)$ time with $O(n^2)$ processors on SIMD-CREW model, so the entire algorithm runs in the worst-case $O(\log^2 n)$ time on SIMD-CREW model. \square

3.2 Parallel algorithms on LARPBS

Theorem 7. Break point graph $B(\pi)$ of permutation π of $\{1, \dots, n\}$ can be constructed in constant bus cycles using $O(n)$ processors on LARPBS.

Proof: processors can exchange data by using one-to-one communication that is a constant time operation, so Algorithm 1 also can run in constant bus cycles on a LARPBS of n processors. \square

Theorem 8. Finding all cycles in BP Graph runs $O(\log n)$ bus cycles on a LARPBS of $O(n)$ processors.

Proof: the parts of lines (5~7) and lines (13~15) of Algorithm 2 both need to use multiple multicasting that takes $O(1)$ time (Lemma 2), and the operation of computing sum (line 23) only needs $O(1)$ time (Lemma 3) which is different from SIMD-CREW model. The iteration part also needs $O(\log n)$ bus cycles, then Algorithm 2 runs $O(\log n)$ bus cycles on a LARPBS of $O(n)$ processors. \square

Theorem 9. Finding components in permutation π performs $O(\log n)$ time using LARPBS of $O(n^3)$ processors.

Proof: The parts of lines (5~19) of Algorithm 3 need to use multiple multicasting that just needs $O(1)$ time as mentioned in Lemma 2, and the parts of lines (6~8) and (14~16) use $O(1)$ time with $O(n^3)$ processors (Lemma 4)

that is different from SIMD-CREW model. The iteration part also needs $O(\log n)$ bus cycles, so Algorithm 3 runs $O(\log n)$ bus cycles on a LARPBS of $O(n^3)$ processors. \square

Lemma 6. Whether a component of $OV(\pi)$ is a hurdle can be determined in constant bus cycles using $O(n)$ processors on LARPBS.

Proof: According to the definition of hurdle, we need two steps to test a component: first, checking whether the component is unoriented component just needs to know whether all edges are unoriented; second, checking if there is no other component between start and end of it except for two-edged simple cycles. Both steps can complete in constant time with n processors in LARPBS. But in LARPBS, we can gather all data in constant time. \square

Theorem 10. The number of hurdles can be counted in constant bus cycles with $O(n^2)$ processors on LARPBS.

Proof: There are $O(n)$ components in the permutation π . All components can be determined in $O(1)$ time using $O(n^2)$ processors as mentioned in Lemma 6. If a component is a hurdle, we set $h(i)=1$, otherwise $h(i)=0$. Parallely computing the sum of $h(i)$ can run $O(1)$ time with $O(n^2)$ processors, as mentioned in Lemma 3. \square

Theorem 11. Whether the permutation is fortress can be determined in constant bus cycles on a LARPBS of $O(n^3)$ processors.

Proof: The proof is the same as Theorem 5. \square

Theorem 12. Computing reversal distance of permutation π performs $O(\log n)$ time on a LARPBS of $O(n^3)$ processors.

Proof: Because the steps of the algorithms at most take $O(\log n)$ time as mentioned before, so the entire algorithm runs in the worst-case $O(\log n)$ time on a LARPBS of $O(n^3)$ processors. \square

4 Conclusions

Two parallel algorithms for computing the reversal distance between two signed permutations have been presented in this paper. The time complexities of the algorithms are $O(\log^2 n)$ on SIMD-CREW model and $O(\log n)$ on LARPBS model. Because certain operations such as computing prefix sum and sorting a smaller set of data can be done in constant time on the LARPBS model, we are able to take advantage of them and to make the algorithm faster than PRAM. We believe many other algorithms can also take advantage of the high communication bandwidth on the LARPBS model. In addition, there are some problems concerning in this paper for the future work, such as, whether the time complexity and computational cost of the algorithm can be further improved. We expect to see more results published in this area in the future.

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